

AMENDMENTS TO THE CLAIMS

1-17. (Canceled)

18. (Previously Presented) A vehicle navigation system comprising:

a computer module including a CPU, map database, first vehicle data, second vehicle data, and at least one of an inertial sensor and a GPS receiver;

said computer module utilizing said first vehicle data when the computer module is installed in the first vehicle and said second vehicle data when said computer module is installed in the second vehicle.

19. (Original) The vehicle navigation system of claim 18 further including a user interface for providing user input regarding whether to use the first vehicle data or the second vehicle data.

20. (Original) The navigation system of claim 19, wherein the user interface includes a display and user operable switches for selecting between the first vehicle data and second vehicle data.

21. (Original) The vehicle navigation system of claim 18, wherein the first vehicle data includes information regarding the orientation of the computer module relative to the first vehicle when the computer module is installed in the first vehicle and the second vehicle data includes information regarding the orientation of the computer module relative to the second vehicle when the computer module is installed in the second vehicle.

22. (Currently Amended) The navigation system of claim 21, wherein the CPU propagates the position of the vehicle navigation system based upon the first vehicle data when the computer module is installed in the first vehicle and based upon the second vehicle data when the computer module is installed in the second vehicle.

23-25. (Canceled)

26. (Previously Presented) A method for using a vehicle navigation system including the steps of:

- a. removably securing a CPU and inertial sensor in a first vehicle;
- b. removing the CPU and at least one inertial sensor from the first vehicle;
- c. after step b., removably securing the CPU and the at least one inertial sensor in a second vehicle,

further including the steps of propagating the position of the first vehicle after said step a. based upon data from the at least one inertial sensor,

further including the step of propagating the position of the second vehicle based upon data from the inertial sensor after said step c.,

further including the steps of:

storing first vehicle data regarding the orientation of the at least one inertial sensor when installed in the first vehicle; and

storing second vehicle data regarding the orientation of the at least one inertial sensor when installed in the second vehicle.

27. (Currently Amended) The method of claim 26 further including the steps of:

propagating the position of the first vehicle based upon the first vehicle data when the CPU and first inertial sensor are installed in the first vehicle; and

propagating the position of the second vehicle based upon the second vehicle data when the CPU and the at least one inertial sensor are installed in the second vehicle.

28. (Original) The method of claim 27 further including the step of manually selecting whether to use the first vehicle data or second vehicle data via a user input device.

29. (Original) The method of claim 28, wherein step a. includes the step of mating said CPU and at least one inertial sensor with a docking station mounted in the first vehicle.

30-38. (Canceled)

39. (Original) A method for using the vehicle navigation system including the steps of:
- a) storing first vehicle data regarding operation of the vehicle navigation system when installed in a first vehicle;
 - b) storing second vehicle data regarding operation of the vehicle navigation system when installed in a second vehicle;
 - c) selectively retrieving either the first vehicle data or the second vehicle data; and
 - d) propagating the position of the vehicle navigation system based upon the first vehicle data or second vehicle data selected in said step c).

40-44. (Canceled)